# **Toturial: Software -** Data Acquisition (DAQ) MEC100x-Lectures 11

Energy, Power and Intelligent Control School of Electronics, Electrical Engineering and Computer Science Ashby Building Queen's University Belfast





# Aims

- 1. DAQ Software :
- 2. NI Device Monitor
  - Digital input test
  - Digital output test
  - Analog input test
  - Analog output test
- 3. MATLAB/SIMULINK and Hardware in Loop with DAQ
  - Digital input

AND and XOR gate in simulink

- Digital output
- Analog input
- Analog output

**Closed-loop control and PID controller in Simulink** 



## DAQ SOFTWARE : INSTALLATION

I- First; Download DAQNavi-offline software from the Advantech website:

https://www.advantech.com/en/support/details/driver?id=I-IYXXIAO

2- Second; Install DAQNavi-offline software.

**DAQNavi-offline** Test Only Document No.1-4289600976 2020-10-12 Driver Related OS: Win10, Win7, WinXP, WinServer2003, WinServer2008 **Related Product:** DAQNavi/SDK Solution: **DAQNavi-offline** Test Only This is for internal test **DAQNavi-offline** 2020-09-24

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Download

## DAQ SOFTWARE : NI DEVICE MONITOR/ TEST

1	Device Detected		
	NI USB-6009		
	Dev1		
F	Test this device using Test Panels	Go	1-
	Begin an application with this device using NI LabVIEW (32-bit)	Go	
¢	Configure and test this device using NI Measurement & Automation Explorer	Go	
0	View online device documentation	Go	ŀ
-0	View device pinouts	Go	1

















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#### **Output voltage and LED module test**









#### **DIGITAL I/OTAB**









### **PIR motion sensor and DAQ Navi**



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acquisition '	Search Results: Data acquisition <<>>> Page 1 of 1 (10 Blocks found)		-		,	
Simulink/ Library	<ul> <li>Simulink         <ul> <li>Commonly Used Blocks</li> <li>Continuous</li> <li>Dashboard</li> <li>Discontinuities</li> <li>Discrete</li> <li>Logic and Bit Operations</li> <li>Lookup Tables</li> <li>Math Operations</li> <li>Model Verification</li> <li>Model Verification</li> <li>Model-Wide Utilities</li> <li>Ports &amp; Subsystems</li> <li>Signal Attributes</li> <li>Signal Routing</li> <li>Sinks</li> <li>Sources</li> <li>String</li> <li>User-Defined Functions</li> <li>Additional Math &amp; Discrete</li> <li>Quick Insert</li> <li>Aerospace Blockset</li> <li>Audio Toolbox</li> <li>AUTOSAR Blockset</li> <li>Communications Toolbox HDL Support</li> <li>Computer Vision Toolbox</li> <li>Control System Toolbox</li> <li>Data Acquisition Toolbox</li> </ul> </li> </ul>	AI/AO/DI/DO Components in MATLAB/SIMULINK		<ul> <li>Data Acquisition Tot</li> <li>A/D</li> <li>Analog Input</li> <li>Single Sample A/D</li> <li>Analog Input (Single Sample)</li> <li>D/A</li> <li>Analog Output</li> <li>Single Sample D/A</li> <li>Analog Output</li> <li>Single Sample D/A</li> <li>Analog Output</li> <li>(Single Sample)</li> <li>Single Sample)</li> <li>Simulink Real-Time</li> <li>YCD CAM</li> </ul>	- 2	

#### I - Digital input(DI)





#### **Digital input (DI) configuration:**





EDU



#### **Digital output (DO) configuration:**



EXAMPLE I

I-IF "sensor I (PIR motion sensor) and sensor 2 (water vapor sensor) are activated, THEN LED digital output should light up".





2- IF "sensor I (PIR motion sensor) is activated and sensor 2 (water vapor sensor) is not activated

#### OR

"sensor I (PIR motion sensor) is not activated **and** sensor 2 (water vapor sensor) is activated **THEN**, the **LED digital output** should light up".







## 3-Analog Input (AI)



#### Analog input (AI) configuration:

ni Dev1 USB-6009

#### Single-ended/ differential type measuring





### 4-Analog output (AO)



AO \* - Simulink academic use

#### Analog output (AO) configuration:







- Let's measure the flow sensor(Analog input) then the measured signal should amplify and then send a command to the Analog output (Proportional actuator).



AIAO \* - Simulink academic use





- Here is a closed-loop control system that used a PID control to generate a control signal:
- The temperature sensor (analog input) measures temperature then PID control sends a command to the analog output (heater driver) to control the heat.







### **Thank You For Your Attention!**

### **Any Question?**





